



PHYS 2350

Kinematics

$$\Delta s = v_{0s}t + \frac{1}{2}a_s t^2$$

$$v_s = v_{0s} + a_s t$$

$$v_s^2 = v_{0s}^2 + 2a_s \Delta s$$

$$\bar{v} = \frac{\Delta s}{\Delta t}$$

$$\bar{a} = \frac{\Delta v}{\Delta t}$$

$$\vec{u} = \vec{u}' + \vec{v}, \text{ relative velocities}$$

$$R = \frac{2v_0^2 \sin \theta \cos \theta}{g}$$

$$H = \frac{v_0^2 \sin^2 \theta}{2g}$$

$$t_{\text{flight}} = \frac{2v_0 \sin \theta}{g}$$

Dynamics

$$\sum \vec{F} = m\vec{a}$$

$$\mathcal{F}_s \leq \mu_s N$$

$$\mathcal{F}_k = \mu_k N$$

$$w = mg, \quad g = 9.8 \text{ m/s}^2$$

Uniform Circular Motion

$$a_{\text{radial}} = -\frac{v_{\text{tangent}}^2}{r}$$

$$a_{\text{tangent}} = 0$$

$$v_{\text{radial}} = 0$$

$$v_{\text{tangent}} = \frac{2\pi r}{T}$$

$$f = \frac{1}{T}$$

Gravitation

$$F_g = \frac{GMm}{r^2}, \quad G = 6.67 \times 10^{-11} \frac{\text{N}\cdot\text{m}^2}{\text{kg}^2}$$

$$\left(\frac{T_1}{T_2}\right)^2 = \left(\frac{a_1}{a_2}\right)^3, \quad a = \text{semimajor axis}$$

$$v^2 = \frac{GM}{r}, \text{ orbits}$$

Work and Energy

$$W_F = F\Delta s \cos \phi$$

$$\bar{P} = \frac{W}{t} = Fv \cos \phi$$

$$KE_T = \frac{1}{2}mv^2$$

$$U_g = \begin{cases} -\frac{GMm}{r} \\ mgy, \text{ if } r \approx R_e \end{cases}$$

$$F_x^{(\text{spring})} = -kx$$

$$U_s = \frac{1}{2}k(\Delta \ell)^2$$

$$KE_1 + U_{g1} + U_{s1} + W^* = KE_2 + U_{g2} + U_{s2}$$

$$W_g = -\Delta U_g$$

$$W_s = -\Delta U_s$$

$$v_{\text{esc}}^2 = \frac{2GM}{R}$$



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Linear Momentum

$$\vec{p} = m\vec{v} \quad \vec{J} = \Delta\vec{p} = \left(\sum \vec{F}\right) \Delta t \quad \text{if } \sum_{\text{ext}} F = 0, p_{\text{initial}} = p_{\text{final}}$$

if elastic collision, $KE_{\text{initial}} = KE_{\text{final}}$, $\epsilon \equiv \frac{v_2 - v_1}{u_1 - u_2} = 1$ for 1-dim

$u_1 + v_1 = u_2 + v_2$, for 1-dim, 2-body, elastic collisions

$$x_{\text{cm}} = \frac{\sum m_i x_i}{\sum m_i}, y_{\text{cm}} = \frac{\sum m_i y_i}{\sum m_i} \quad \text{if } \sum_{\text{ext}} F = 0 \text{ \& } p_{\text{system}} = 0, \text{ then } \Delta x_{\text{cm}} = 0 \text{ (} \sum m_i x_i = \sum m_i x_i')$$

Rotational Motion

$$\bar{\omega} = \frac{\Delta\theta}{\Delta t}$$

$$\bar{\alpha} = \frac{\Delta\omega}{\Delta t}$$

$$\omega = 2\pi f$$

$$\Delta\theta = \omega_0 t + \frac{1}{2}\alpha t^2$$

$$\omega = \omega_0 + \alpha t$$

$$\omega^2 = \omega_0^2 + 2\alpha\Delta\theta$$

$$a_{\text{radial}} = -r\omega^2$$

circular \Rightarrow $a_{\text{tangent}} = r\alpha$

motion \Rightarrow $v_{\text{tangent}} = r\omega$

$$\Delta s = r\Delta\theta$$

$$\tau = \begin{cases} rF \sin \phi \\ rF_{\perp} \\ r_{\perp} F \end{cases}$$

$$\sum \tau = \frac{\Delta L}{\Delta t} \quad L = rp \sin \phi = r_{\perp} p$$

if $\sum_{\text{ext}} \tau = 0$, $L_{\text{initial}} = L_{\text{final}}$

rigid rotator

about O' ,

O' is stat. pt. or c.m.

$$\sum \tau = I_{O'} \alpha$$

$$L = I_{O'} \omega$$

$$W = W_{F \text{ on } O'}^{(\text{pseudo})} + W_R \text{ about } O'$$

$$KE = KE_T \text{ of } O' + KE_R \text{ about } O'$$

$$W_R = \tau \Delta\theta \cos \phi$$

$$P = \tau \omega \cos \phi$$

$$KE_R = \frac{1}{2} I \omega^2$$

$$I = \sum m r_{\perp}^2$$

$$I_{\parallel} = I_{\text{cm}} + m d^2$$

$$I_{\text{center rod}} = \frac{1}{12} m \ell^2$$

$$I_{\text{loop}} = m r^2$$

$$I_{\text{cylinder}} = \frac{1}{2} m r^2$$

$$I_{\text{sphere}} = \frac{2}{5} m r^2$$

rolling, no

slipping

$$a_{\text{cm}} = r\alpha$$

$$\Rightarrow v_{\text{cm}} = r\omega$$

$$\Delta s_{\text{cm}} = r\Delta\theta$$



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Fluids

$$\bar{\rho} = \frac{m}{V} \quad \rho_{\text{water}} = 1000 \text{ kg/m}^3 \quad SG = \frac{\rho}{\rho_w} \quad P = \frac{F_{\perp}}{A} \quad \Delta P_{\text{fluid}} = \rho_{\text{fluid}} g \Delta y$$

$$P_{\text{atm}} = 1.013 \times 10^5 \text{ Pa} \quad P^{(\text{absolute})} = P_{\text{atm}} + \Delta P^{(\text{gauge})} \quad B = \rho_{\text{fluid}} g V_{\text{displaced}}$$

$$Q = \frac{\Delta V}{\Delta t} = A_1 v_1 = A_2 v_2 \quad P_1 + \rho g y_1 + \frac{1}{2} \rho v_1^2 = P_2 + \rho g y_2 + \frac{1}{2} \rho v_2^2$$

Vibration and Waves

$$f = \frac{1}{T} = \frac{\omega}{2\pi}$$

$$E_{\text{total}} = \frac{1}{2} m v^2 + \frac{1}{2} k x^2 = \frac{1}{2} k A^2$$

mass-spring: $v = \pm \omega \sqrt{A^2 - x^2}$, $\omega = \sqrt{\frac{k}{m}}$

$$a = -\omega^2 x$$

$$v_{\text{max}} = \omega A$$

$$a_{\text{max}} = \omega^2 A$$

$$x(t) = A \sin(\omega t + \delta)$$

mass-spring: $v(t) = \omega A \cos(\omega t + \delta)$, $\tan \delta = \frac{\omega x_0}{v_0}$

$$a(t) = -\omega^2 A \sin(\omega t + \delta)$$

simple pendulum: $T = 2\pi \sqrt{\frac{L}{g}}$

physical pendulum: $T = 2\pi \sqrt{\frac{I_0}{mgd}}$

$$f\lambda = v$$

string: $f_n = n \left(\frac{v}{2L}\right)$, $n = 1, 2, 3, \dots$

$$v = \sqrt{\frac{T}{\mu}}, \mu = \frac{m}{L}$$

$$\bar{I} = \frac{P}{S} \text{ (if spherical wave, } S = 4\pi r^2)$$

$$I = 2\pi^2 v \rho f^2 A^2$$

Sound

$$v_{\text{sound}} = 331 \sqrt{\frac{T_K}{273}} \text{ [m/s]} \quad \beta = 10 \log \frac{I}{I_0}, I_0 = 10^{-12} \text{ W/m}^2, I = I_0 10^{\frac{\beta}{10}}$$

pipes: $f_n = n \left(\frac{v}{2L}\right)$, $n = 1, 2, 3, \dots$, open

$$f_n = m \left(\frac{v}{4L}\right)$$
, $m = 1, 3, 5, \dots$, closed

$$f_{\text{beat}} = |f_1 - f_2| \quad \frac{f_L}{v+v_L} = \frac{f_S}{v+v_S}, L \leftrightarrow S$$



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Temperature and Kinetic Theory

$T_C = \frac{5}{9}(T_F - 32)$	$\frac{P}{RT} = \frac{n}{V} = \frac{\rho}{M}, R = 8.315 \text{ J}/(\text{mol} \cdot \text{K})$	$n = \frac{N}{N_A} = \frac{M}{M}$
$T_K = T_C + 273.15$	$1 \text{ atm} = 1.013 \times 10^5 \text{ Pa}$	$m = \frac{M}{N_A}$
$\overline{KE}_{\text{gas molec}} = \frac{1}{2}m\overline{v^2} = \frac{3}{2}k_B T$		
$v_{\text{rms}} = \sqrt{\frac{3RT}{M}}$		
$k_B = R/N_A, N_A = 6.022 \times 10^{23} \text{ mole}^{-1}$		

Heat

$(Q + W^{(\text{on})})_{\text{IS}} = 0$	$Q_{\text{temp change}} = mc\Delta T$	$Q > 0, \text{ absorbed}$	$\dot{Q}_{\text{conv}} = hA(T_{\infty} - T_{\text{surf}})$
	$Q_{\text{phase change}} = \pm mL_{S,F,V}$	$Q < 0, \text{ released}$	
$\dot{Q}_{\text{cond}} = -kA\frac{\Delta T}{\Delta s}$	$1 \text{ cal} = 4.186 \text{ J}$	$c_{\text{water}} \approx 2c_{\text{ice}} = 1 \text{ cal}/(\text{g} \cdot \text{C}^0)$	
$\dot{Q}_{\text{rad}} = e\sigma A(T_{\text{surr}}^4 - T_{\text{body surf}}^4)$	$\sigma = 5.67 \times 10^{-8} \text{ W}/(\text{m}^2 \cdot \text{K}^4)$	$L_F^{(\text{H}_2\text{O})} = 80 \text{ cal/g}$	

Thermodynamics

$\Delta U = Q - W^{(\text{by})}, \text{ 1st law}$	$W_{\Delta P=0} = P\Delta V$	$W > 0, \text{ done by}$
$W = \text{area under } PV \text{ curve}$	$W_{\Delta T=0} = nRT \ln\left(\frac{V_{\text{fin}}}{V_{\text{ini}}}\right), \text{ ideal gas}$	$W < 0, \text{ done on}$

$Q_{\Delta V=0} = nC_V\Delta T$	$\Delta U = nC_V\Delta T, \text{ ideal gas}$	$\Delta S_{\text{q.s.}} = \sum \frac{\delta Q}{T} \approx \frac{Q}{T}$
$Q_{\Delta P=0} = nC_P\Delta T$	$C_V = \frac{3}{2}R, \text{ monatomic}$	$\Delta S_{\text{IS}} \geq 0, \text{ 2nd law}$
	$C_P = C_V + R$	
	$PV^\gamma = \text{const.}, \gamma = \frac{C_P}{C_V}, \text{ adiabats}$	

$\Delta U_{\text{cycle}} = 0$	$\left. \begin{aligned} \varepsilon &= \frac{W}{Q_H}, \text{ heat engine} \\ \kappa &= -\frac{Q_L}{W}, \text{ refrigerator} \end{aligned} \right\} \text{ Carnot cycle}$
$W_{\text{cycle}} = Q_H + Q_L$	
$\Delta S_{\text{cycle}} = 0$	
	$\left. \begin{aligned} -\frac{Q_L}{Q_H} &= \frac{T_L}{T_H} \\ \varepsilon_{\text{Carnot}} &= 1 - \frac{T_L}{T_H} \\ \kappa_{\text{Carnot}} &= \frac{T_L}{T_H - T_L} \end{aligned} \right\}$